



#### Digital Twin of the Ocean: Sensors in DTOs

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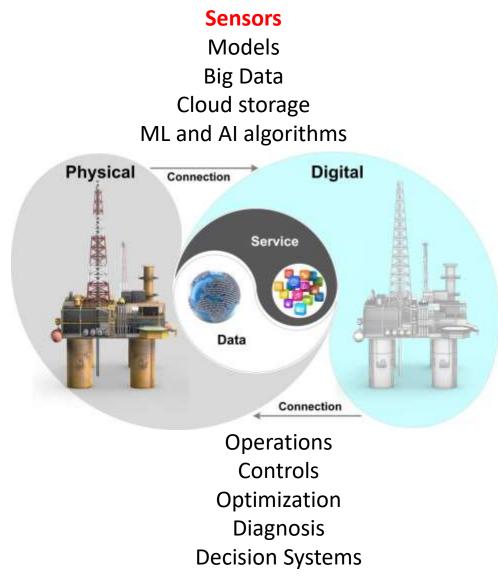
Date:

12 July 2024

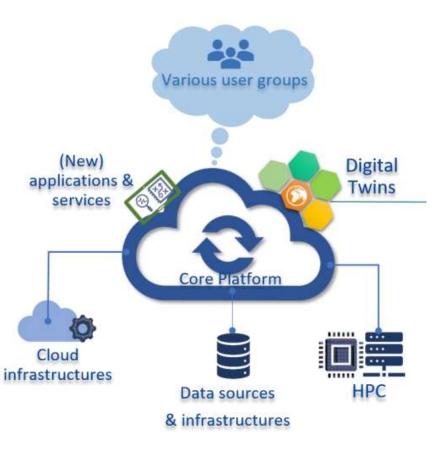


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#### DTs in Industry 4.0











# ILIAD Pilot DTs

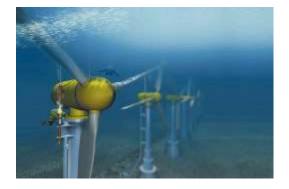




Offshore Wind Energy Farms



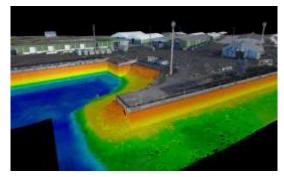
Onshore Wave Energy Farms



Tidal Energy Farms



Fisheries/Aquaculture



Harbor Safety



Mucilage/Oil Spills

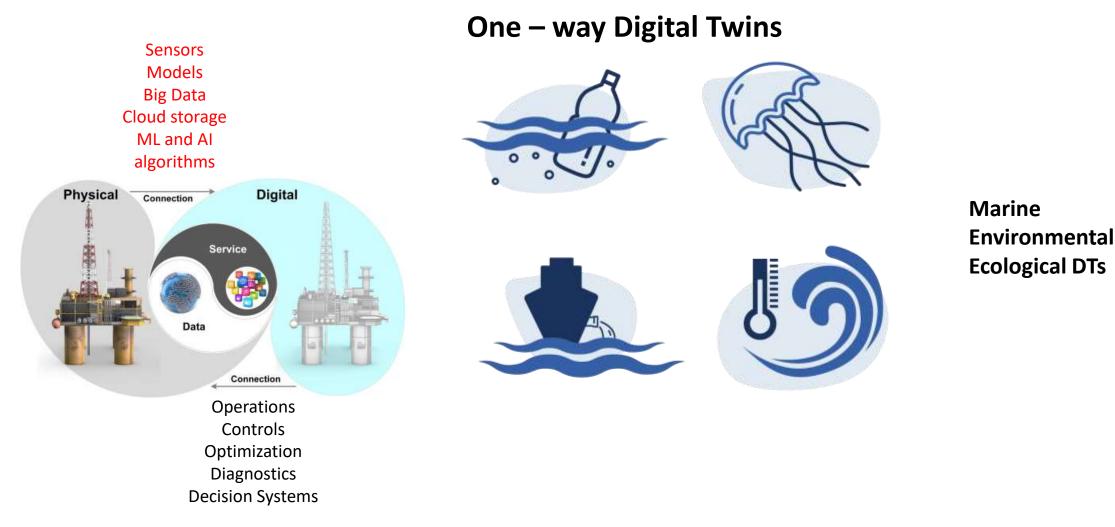


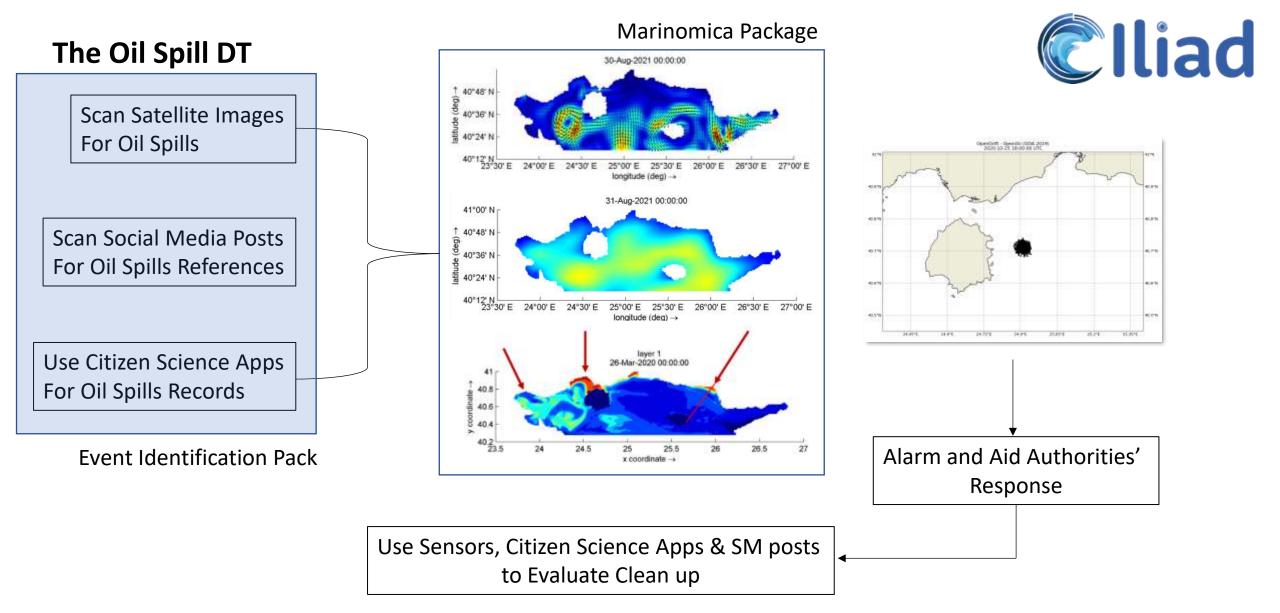


#### **ILIAD Pilots Classification**

A DT is a real-time digital replica of a physical entity, in which the real part can be mirrored in a virtual environment and continuously updated from multiple sources for various purposes (Fuller et al., 2019).

CIliad









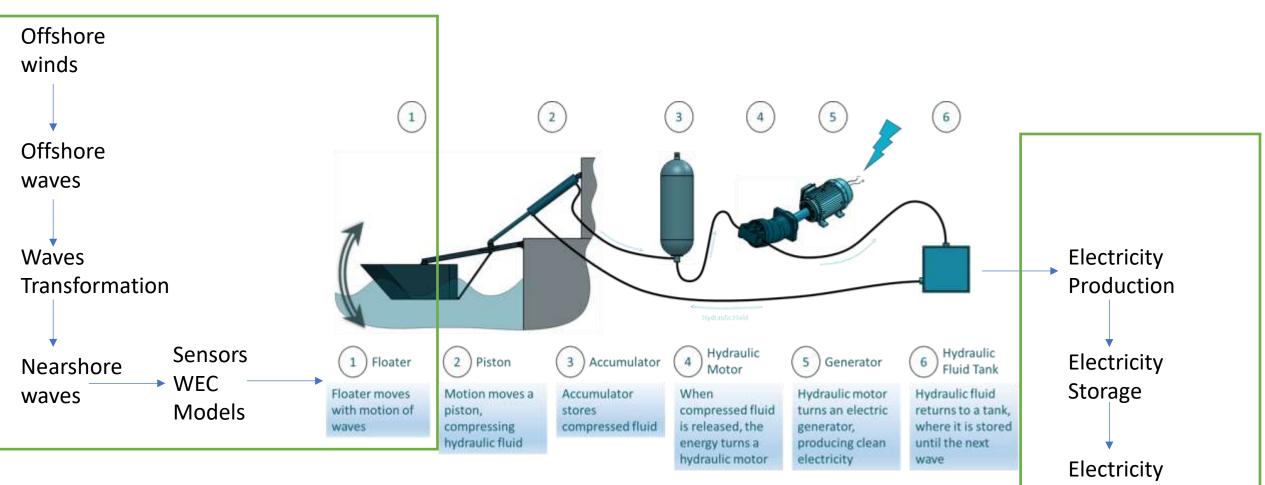
#### CIliad

#### **ILIAD Pilots Classification**

A DT is a digital replica that maintains data and dynamics information in parallel with every individual component of a real-time system (Kim et al., 2020).



#### The WEC DT



CIliad

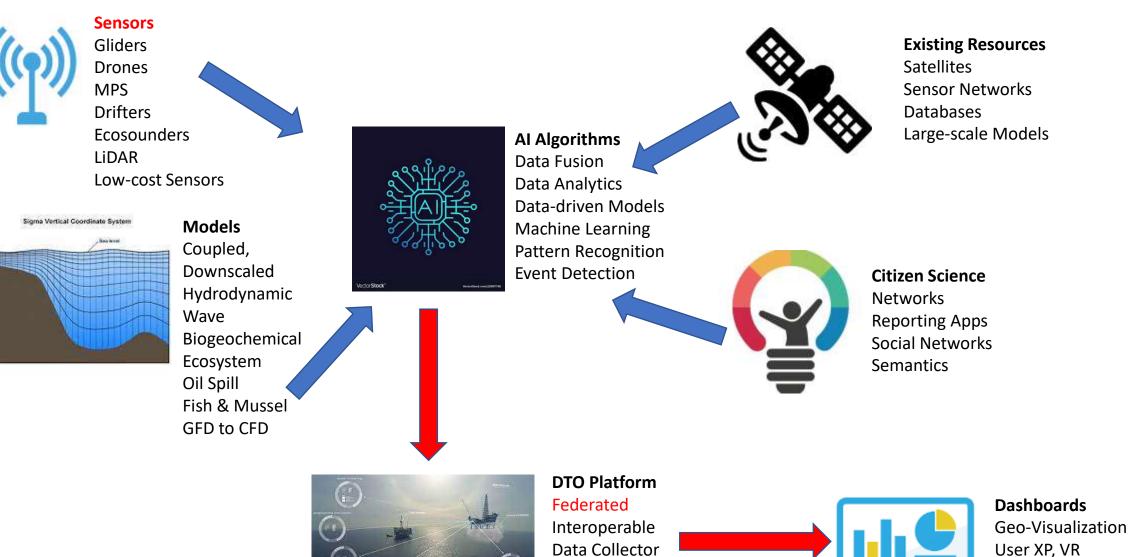
Grid



Wave farm optimization layout; operational decision-making; prevention of mechanical damage from extreme wind/wave loadings; corrosion alert; Operational prognostics; siting assessment.

#### **ILIAD Digital Twin Ingredients and Novelties**

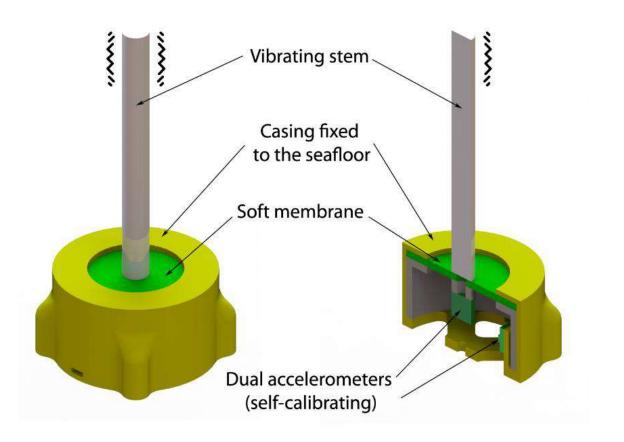




Simulator

**Control Room** 

## Sensors in ILIAD – Hydromast (Taltech)



Hydromast was developed within H2020 Project LakHsMi

- Ship wake detection and ship traffic monitoring
- Wave action monitoring
- Surf zone bedload flow speed monitoring
- Current monitoring







# Flow and wave meter: Hydromast (TalTech)



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The **hydromast** is a flow and water level point measurement device. The hydromast allows to measure instantaneous flow changes based on the tilt of a cylindrical mast on the device and continuous average flow magnitudes based on vortex induced vibrations on the same mast. The incorporated pressure sensor on the device allows to measure changes of the water column and also waves if installed in close vicinity of the water surface.

	Mechanical	Electrical	Connectivity		Maintenance	Collection of Data
Specifications	Base: 80x45mm, total height up to 400 mm, depending on desired velocity range Material: POM, stainless steel, mast covered with Cu sheet Fixation: Upright, bottom mounted Connection: Wet SeaCon 4-pin connectors	Input Voltage: 5 – 12 V (possible to extend to 30V) POE available Data Rate: Interval, sampling rate 50 Hz Data logging: RS485 serial or stand-alone logging with batteries	Ethernet GSM(2G,3G,4G) WiFi LoRaWAN Serial: RS-485	Requisites	Once per 3 months On demand basis	Through AWS IoT service using secured MQTT protocol Local storage of data possible

Next steps for deployment (including estimated dates):

- Offline tests and validations done on sediment study by TalTech (August 2022)
- Sensor deployed at: Talin, Crete (Heraklion) and Israel (Jaffa)
- LoRaWan protocol tests ongoing (started March 2023)

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• Sensors available to partners: Varna port, Adriatic coast (AMA), Valencia port, Iraklion Port

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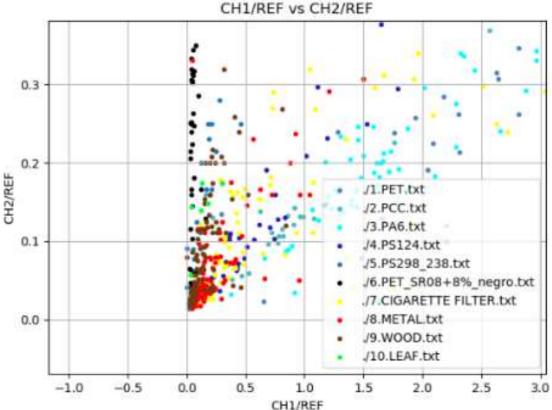


## Sensors in ILIAD – MPS (LEITAT)

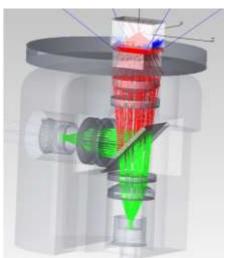


MPS monitoring based on the RT analysis of the fluorescence light emitted by plastic particles when they are excited with a UV light

source.



vin



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# UAV Video Analysis and Reporting (Alpha)



Alpha develops an app that, based on Al video analysis generates reports and/or notifications upon the occurrence of an detection event. The app will be used to (1) detect external damages on the structure of wind turbines; and (2), early detection of off-shore jellyfish swarms. In both cases it will generate an image with metadata about its location. The image(s) will be sent to the pilot servers, enabling to trigger automated actions using its information, such as notifications or the generation of maintenance reports.

	Software features		Collection of Data
Specifications	<ul> <li>Real time video analysis of video feed.</li> <li>Configurable confidence threshold and detection parameters</li> <li>Scalable, being able to use CPU, GPU or Multi - GPU racks for video analysis.</li> <li>Able to ingest remote video feed to use remote processing power.</li> <li>Adaptable to every drone model exposing an interface</li> </ul>	Requisites	<ul> <li>Detection models need to be trained in advance</li> <li>UAV Autopilot need to expose an interface to gather its location information.</li> <li>Nvidia RTX 2060 or better are recommended to obtain decent FPS in the analysis.</li> </ul>

Next steps for deployment (including estimated dates):

- Gather additionally imagery and train models (06/24)
- Finalize app development (06/24)

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### Sensors in WP2 – SeaExplorer (Alseamar)



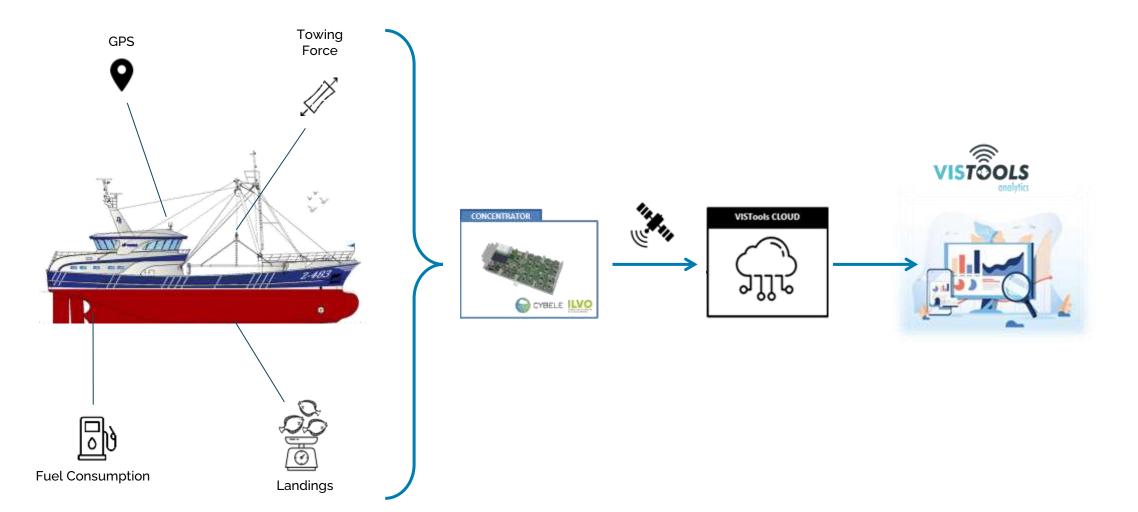
Alseamar will perform 12 months data acquisition with gliders, equipped with 2 different payloads:

- the anoxia payload equipped with sensors like CTD, Chla, turbidity, CDOM, Dissolved Oxygen, Methane, Hydrogen Sulphide and CO2,
- (2) the ecological payload CTD, Chl-a, turbidity, CDOM, zooplankton.





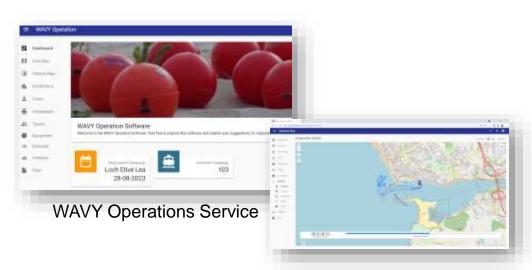
#### **Sensors in WP2 – ILVO sensors**







# WAVY - User Applications



(selected) features:

- operations planning
- deployments management
- data management
- data processing
- datasets management and curation



#### (selected) features:

- real time
- open access
- limited disclosure of the data
- Involve general public in campaigns

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Wavy configuration App

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# Fishing Effort Sensors (ILVO)



Sensors	Data Collection	Data Storage	Analytics	Visualisation	
GPS, Fuel, Scale and Towing force	3 vessels operational 2 vessels incomplete sensors	Operational, scaleable	basic analytics completed Scaleable -	operational for 4 vessels (PowerBI) Scaleable	Towing Force
TD sensor (Moana)	installed on 3 vessels (2 vessels sending data)	Operational, scaleable	coupling to tow/trip done – link to R package	In R	111 50.9904" N
CTD and TBD sensor (NKE)	vessel A has CTD and vessel B has TBD	operational (when data is received), scaleable	coupling to tow/trip done – link to R package	In R	GPS
Weather station	installed on 2 vessels	servers ready to receive data	coupling to tow/trip done – link to R package	In R	Engine



Scale



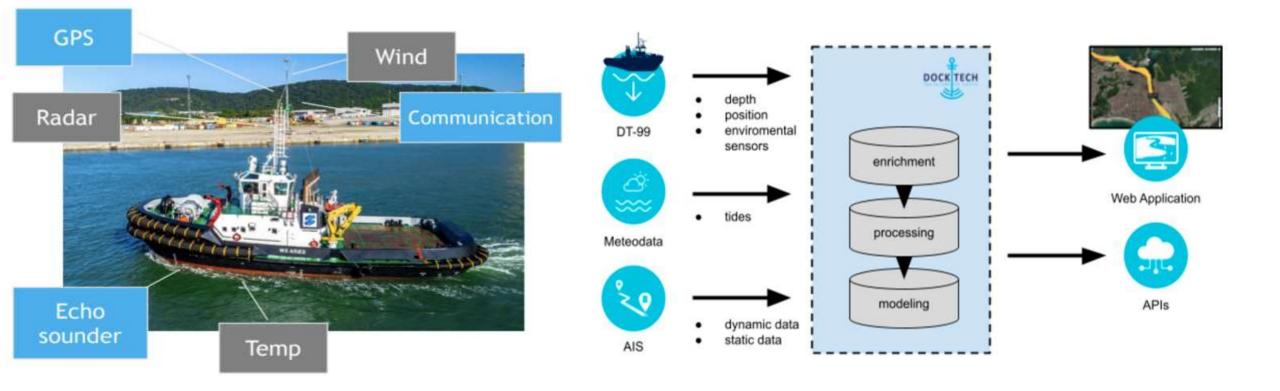
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Concentrator (centralisation of data)



## **Sensors in ILIAD – DockTech sensors**



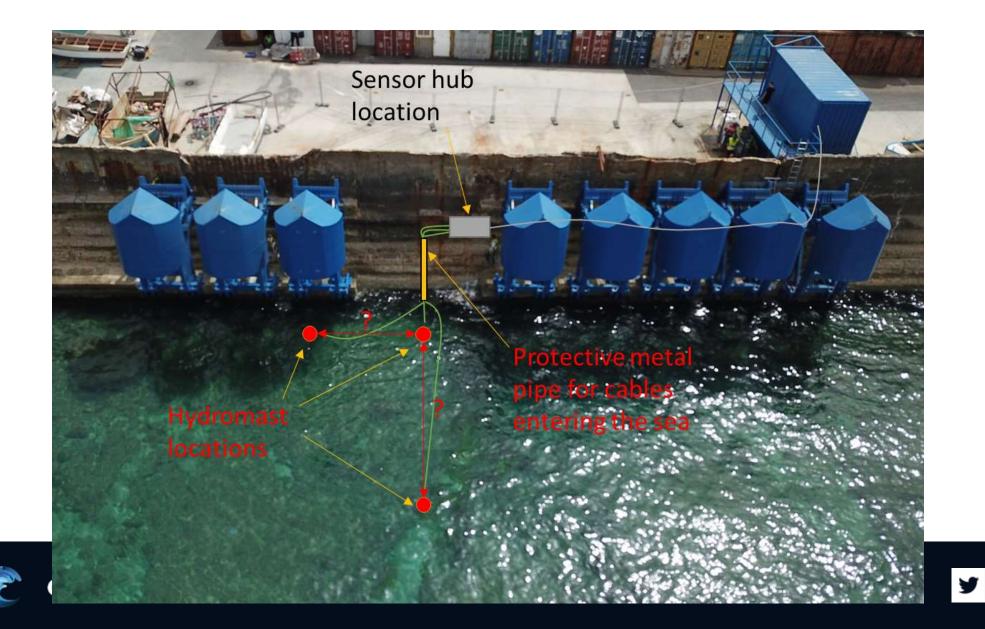




## Sensors in Operation at Jaffa Port – WEC DT



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# Data acquisition and Retrieval – Oil Spill DTs



In-situ data for the Cretan Sea Oil Spill pilot are also provided by HCMR's <u>Poseidon System</u> Fixed Mooring Buoys



Meteorological data (wind speed and direction, air temperature, humidity, precipitation) from local meteorological stations and NOAA METAR observations

Sentinel-1 images to detect oil spills





Image credit: NA



Marine Copernicus Med Sea Physics & Waves products:<u>MEDSEA\_ANALYSI</u> <u>SFORECAST\_PHY\_006\_013</u> <u>MEDSEA\_ANALYSISFOREC</u> <u>AST\_WAV\_006\_017</u>

NOAA GFS solution 0.250 resolution

**GEBCO** bathymetry

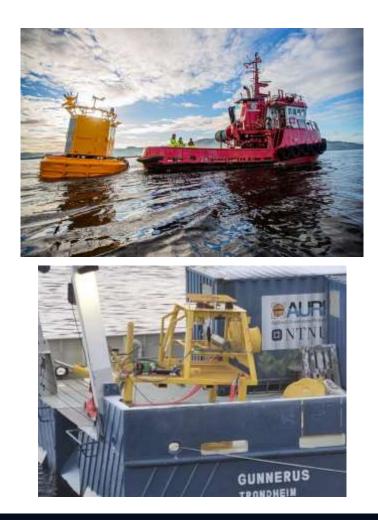




# Buoys and benthic Lab | Lander – Water Quality DT

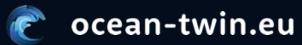






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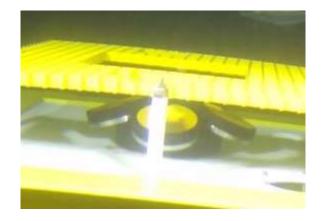






# Buoys and benthic Lab | Lander – Water Quality DT







ADCP and CTD from the benthic station





Weather station and SilCam on the buoy





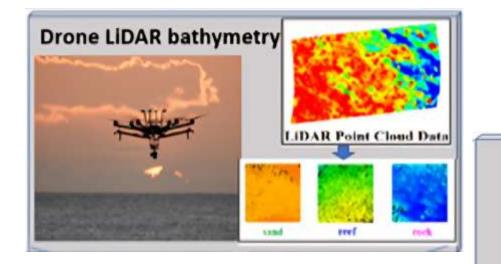
Microplastic sensor testing on the buoy

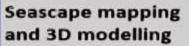


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## Data acquisition | input data – Biodiversity and SeaScape DT

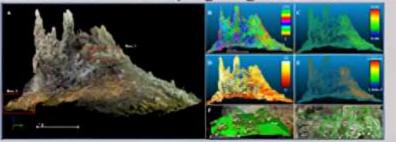








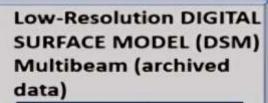
Structure from motion, High regulation DSM model

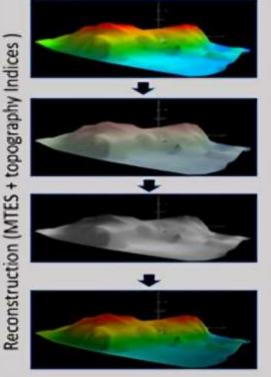


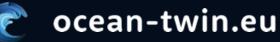


Mapping the location of target fish species











# Data Acquisition and RT Transfer | Oil Spill DT

#### Kariani's Buoy

#### Time Range: 26/10/2018 - Present Time Step: 1 hr

#### Parameters

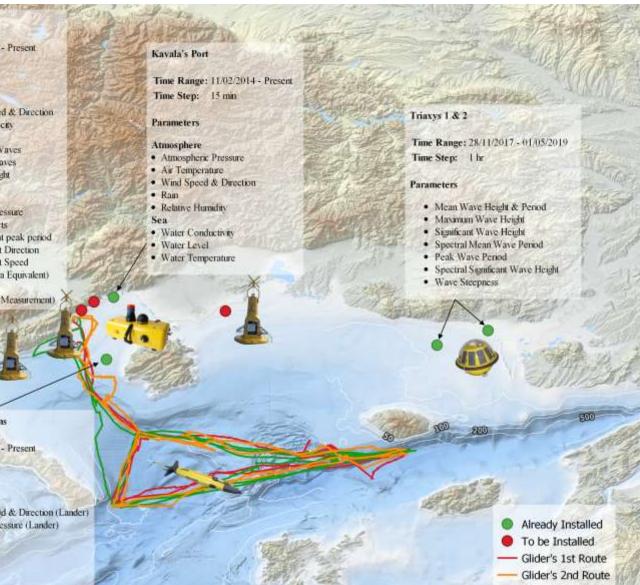
- · Profile Currents Speed & Direction
- · Profile U. V. W Velocity
- · Wave Peak Period
- Mean 1/10 Largest Waves
- · Mean 1/3 Largest Waves
- · Stanificant Wave Height
- · Maximum Wave
- Mean Direction
- · Mean Hydrostatic Pressure
- Number of No Detects
- Directional variance at peak period
- Near Surface Current Direction
- · Near Surface Current Speed
- Mean Period (Spectra Equivalent)
- Peak Period
- Mean Period (Direct Measurement)

#### Lander & Surface Systems

Time Range: 13/07/2020 - Present Time Step: 1 hr

#### **Parameters**

- Profile Currents Speed & Direction (Lander)
- Mean Hydrostatic Pressure (Lander)
- · Dissolved Oxygen
- · Ar Saturation
- Water Temperature
- Water Conductivity
- · Chlorophyll
- Turbidity





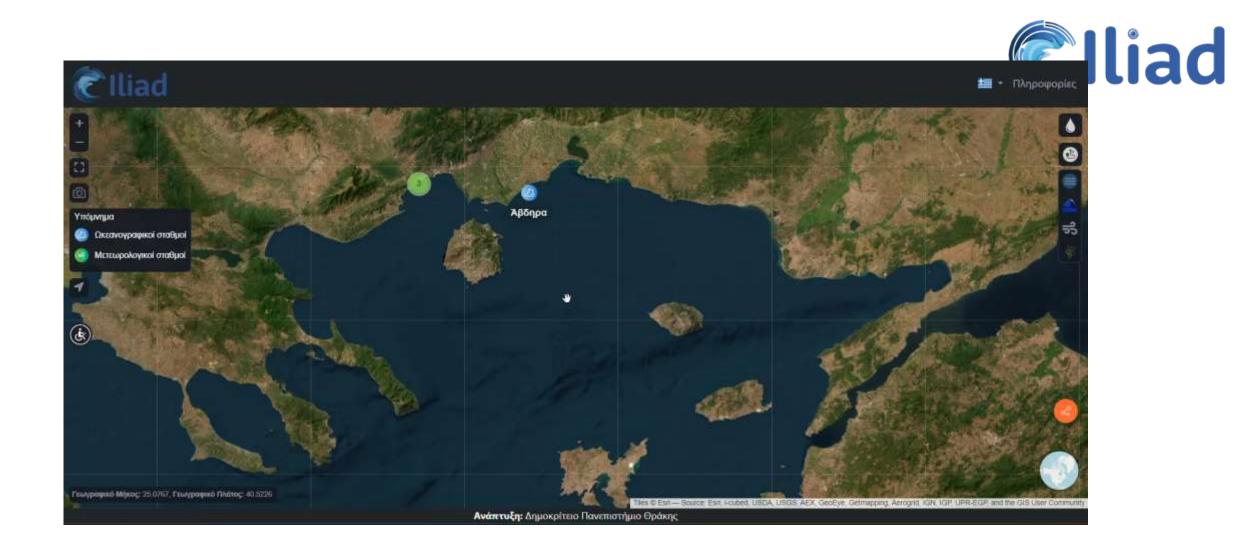
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- 4 ADCPs for 3D currents, waves and SPM monitoring
- 1 surface water quality station (SST, S, DO, Chl, pH, SPM)
- 2 Wave riders (wave height, period and direction)
- Glider surveys (T, C, S,  $\sigma_{t}$ , CDOM, SPM, DO)

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Glider's 3rd Route











Thank You

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